MA 1201 : Mathematics II

Satvik Saha, 19MS154

Problem 1 Show that the vectors (a, b) and (c, d) in \mathbb{R}^2 are linearly independent iff $ad - bc \neq 0$.

Solution We first let (a, b) and (c, d) be linearly independent. Now, if ad - bc = 0, then without loss of generality, either a = b = 0, in which case (a, b) is the zero vector (0, 0), or a = 0 and d = 0, in which case one of b or c is also 0, so one of (a, b) and (c, d) is the zero vector (0, 0), or a = 0, $d \neq 0$ and c = 0, in which case

$$d(0,b) + (-b)(0,d) = (0,0),$$

or $a, b, c, d \neq 0$, in which case

$$c(a,b) + (-a)(c,d) = (0,0)$$

This is a contradiction, hence we must have $ad - bc \neq 0$.

Now we assume $ad - bc \neq 0$. If (a, b) and (c, d) were linearly dependent, we find λ , μ , at least one of which is non-zero, such that

$$\lambda(a,b) + \mu(c,d) = (0,0),$$

i.e. $\lambda a = -\mu c$ and $\lambda b = -\mu d$. If $\mu = 0$, that forces a = b = 0, and hence ad - bc = 0. Similarly, $\lambda = 0$ forces c = d = 0, and hence ad - bc = 0. Finally, for $\lambda, \mu \neq 0$, we have

$$\lambda \mu (ad - bc) = (\lambda a)(\mu d) - (-\lambda b)(-\mu c) = 0,$$

and thus ad - bc = 0. In all cases, we reach a contradiction. Hence, (a, b) and (c, d) must be linearly independent.

Problem 2 Show that if v and w are linearly independent vectors in \mathbb{R}^2 , then so are v + w and v - w.

Solution We assume the contrary, i.e. we find λ and μ , at least one of which is non-zero, such that

$$\lambda(v+w) + \mu(v-w) = 0 \implies (\lambda+\mu)v + (\lambda-\mu)w = 0.$$

The linear independence of v and w demands both $\lambda + \mu = 0$ and $\lambda - \mu = 0$. However, this is only possible if $\lambda = \mu = 0$. This is a contradiction. Hence, v + w and v - w must be linearly independent. \Box

Problem 3 Show that the following are bases of \mathbb{R}^2 .

- (i) $\{(1,2), (4,3)\}.$
- (ii) $\{(1,1), (1,-1)\}.$

Solution

(i) Let $(a,b) \in \mathbb{R}^2$ be arbitrary. We seek $\lambda, \mu \in \mathbb{R}$ such that

$$\lambda(1,2) + \mu(4,3) = (a,b)$$

Solving the system of equations

$$\lambda + 4\mu = a$$
$$2\lambda + 3\mu = b$$

we find $\lambda = (-3a + 4b)/5$ and $\mu = (2a - b)/5$.

April 28, 2020

We now show that this is a unique solution. Let (λ_1, μ_1) and (λ_2, μ_2) be two pairs of solutions to the above system. If

$$\lambda_1(1,2) + \mu_1(4,3) = \lambda_2(1,2) + \mu_2(4,3) = (a,b)$$

then

$$(\lambda_1 - \lambda_2)(1,2) + (\mu_1 - \mu_2)(4,3) = \mathbf{0}.$$

Using the result in Problem 1, we find that (1, 2) and (4, 3) are linearly independent, since $1 \cdot 3 - 2 \cdot 4 \neq 0$. Thus, we must have $\lambda_1 - \lambda_2 = \mu_1 - \mu_2 = 0$, thus proving uniqueness.

Hence, any arbitrary vector in \mathbb{R}^2 can be uniquely expressed as a linear combination of the two given vectors, i.e. they comprise a basis of \mathbb{R}^2 .

(ii) Let $(a, b) \in \mathbb{R}^2$ be arbitrary. Again, we seek $\lambda, \mu \in \mathbb{R}$ such that

$$\lambda(1,1) + \mu(1,-1) = (a,b).$$

Solving the system of equations

$$\lambda + \mu = a$$
$$\lambda - \mu = b$$

we find $\lambda = (a+b)/2$ and $\mu = (a-b)/2$.

We now show that this is a unique solution. Let (λ_1, μ_1) and (λ_2, μ_2) be two pairs of solutions to the above system. If

$$\lambda_1(1,1) + \mu_1(1,-1) = \lambda_2(1,1) + \mu_2(1,-1) = (a,b),$$

then

$$(\lambda_1 - \lambda_2)(1, 1) + (\mu_1 - \mu_2)(1, -1) = \mathbf{0}.$$

Using the result in Problem 1, we find that (1,1) and (1,-1) are linearly independent, since $1 \cdot 1 - 1 \cdot (-1) \neq 0$. Thus, we must have $\lambda_1 - \lambda_2 = \mu_1 - \mu_2 = 0$, thus proving uniqueness.

Hence, any arbitrary vector in \mathbb{R}^2 can be uniquely expressed as a linear combination of the two given vectors, i.e. they comprise a basis of \mathbb{R}^2 .

Problem 4 Show that any set containing 3 vectors in \mathbb{R}^2 is linearly dependent. Also show that any linearly independent set of 2 vectors in \mathbb{R}^2 is a basis of \mathbb{R}^2 .

Solution Let $u, v, w \in \mathbb{R}^2$ be arbitrary, with $u = (u_1, u_2)$, $v = (v_1, v_2)$ and $w = (w_1, w_1)$. Note that if any two of u, v, w are linearly dependent, say u and v, then all three are linearly dependent, i.e. if $c_1, c_2 \in \mathbb{R}$, where at least one of them is non-zero, then

$$c_1u + c_2v = 0 \implies c_1u + c_2v + 0w = \mathbf{0}.$$

Contrapositively, if u, v, w are all linearly independent, then any two of them, say u and v, are also linearly independent.

Assume u, v and w are linearly independent. Then, u and v are linearly independent, i.e. $\Delta_w = u_1v_2 - u_2v_1 \neq 0$. Consider the system of equations

$$\lambda u_1 + \mu v_1 = w_1$$

$$\lambda u_2 + \mu v_2 = w_2$$

It is easily verified that $\lambda = (w_1v_2 - w_2v_1)/\Delta_w$ and $\mu = (u_1w_2 - u_2w_1)/\Delta_w$ is a solution to the above system. Moreover, since u and w are linearly independent, $\Delta_v = u_1w_2 - u_2w_1 \neq 0$ and since w and v are linearly independent, $\Delta_u = w_1v_2 - w_2v_1 \neq 0$. Thus, $\lambda, \mu \neq 0$. However, this means that

$$\lambda u + \mu v - w = \mathbf{0}.$$

This is a contradiction. Hence, any set of 3 vectors in \mathbb{R}^2 must be linearly dependent.

Let $u, v \in \mathbb{R}^2$ be linearly independent. We show that they form a basis of \mathbb{R}^2 . Let $w \in \mathbb{R}^2$ be arbitrary. Like before, we define

$$\begin{aligned} \Delta_w &= u_1 v_2 - u_2 v_1, \\ \Delta_v &= u_1 w_2 - u_2 w_1, \\ \Delta_u &= w_1 v_2 - w_2 v_1. \end{aligned}$$

The linear independence of u and v means that $\Delta_w \neq 0$. Again, it is easily verified that $\lambda u + \mu v = w$, where $\lambda = \Delta_u / \Delta_w$ and $\mu = \Delta_v / \Delta_w$. Furthermore, this solution is unique since if

$$\lambda_1 u + \mu_1 v = \lambda_2 u + \mu_2 v = w,$$

then we must have

$$(\lambda_1 - \lambda_2)u + (\mu_1 - \mu_2)v = \mathbf{0}$$

The linear independence of u and v demands $\lambda_1 - \lambda_2 = \mu_1 - \mu_2 = 0$.

Hence, an arbitrary vector in $w \in \mathbb{R}^2$ can always be uniquely represented as a linear combination of two linearly independent vectors $u, v \in \mathbb{R}^2$, i.e. $\{u, v\}$ form a basis of \mathbb{R}^2 .

Problem 5 Let $T: \mathbb{R}^2 \to \mathbb{R}^3$, $T(x_1, x_2) = (x_1, x_2, 0)$. Show that T is linear and find the matrix of T with respect to the standard bases of \mathbb{R}^2 and \mathbb{R}^3 .

Solution Let $x_1, x_2, y_1, y_2, c \in \mathbb{R}$ be arbitrary. We verify

$$T(\mathbf{x}) + T(\mathbf{y}) = (x_1, x_2, 0) + (y_1, y_2, 0) = (x_1 + y_1, x_2 + y_2, 0) = T(x_1 + y_1, x_2 + y_2) = T(\mathbf{x} + \mathbf{y}),$$

$$cT(\mathbf{x}) = c(x_1, x_2, 0) = (cx_1, cx_2, 0) = T(cx_1, cx_2) = T(c\mathbf{x}).$$

Hence, T is linear. Let $V = {\mathbf{v_1}, \mathbf{v_2}}$ and $W = {\mathbf{w_1}, \mathbf{w_2}, \mathbf{w_3}}$ be the standard bases of \mathbb{R}^2 and \mathbb{R}^3 respectively. Then,

$$[T]_V^W = ([T(\mathbf{v_1})]_W \quad [T(\mathbf{v_2})]_W) = (T(1,0) \quad T(0,1)) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}.$$

Problem 6 Let $T: \mathbb{R}^2 \to \mathbb{R}^2$, $T(x_1, x_2) = (2x_1, -3x_2)$. Show that T is linear and find the matrix of T with respect to the standard basis of \mathbb{R}^2 .

Solution Let $x_1, x_2, y_1, y_2, c \in \mathbb{R}$ be arbitrary. We verify

$$T(\mathbf{x}) + T(\mathbf{y}) = (2x_1, -3x_2) + (2y_1, -3y_2) = (2x_1 + 2y_1, -3x_2 - 3y_2) = T(x_1 + y_1, x_2 + y_2) = T(\mathbf{x} + \mathbf{y}),$$

$$cT(\mathbf{x}) = c(2x_1, -3x_2) = (2cx_1, -3cx_2, 0) = T(cx_1, cx_2) = T(c\mathbf{x}).$$

Hence, T is linear. Clearly,

$$[T] = (T(1,0) \quad T(0,1)) = \begin{pmatrix} 2 & 0 \\ 0 & -3 \end{pmatrix}$$

Problem 7 Let $T: \mathbb{R}^2 \to \mathbb{R}^3$, T(x, y) = (x, x + y, y). Find the matrix of T with respect to the standard bases of \mathbb{R}^2 and \mathbb{R}^3 .

Solution Let $V = {\mathbf{v_1}, \mathbf{v_2}}$ and $W = {\mathbf{w_1}, \mathbf{w_2}, \mathbf{w_3}}$ be the standard bases of \mathbb{R}^2 and \mathbb{R}^3 respectively. Then,

$$T(\mathbf{v_1}) = \begin{pmatrix} 1\\1\\0 \end{pmatrix}, \quad T(\mathbf{v_2}) = \begin{pmatrix} 0\\1\\1 \end{pmatrix}.$$

Thus,

$$[T] = (T(\mathbf{v_1}) \quad T(\mathbf{v_2})) = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{pmatrix}.$$

Problem 8

- (i) Show that $\{(2,1,1), (1,2,2), (1,1,1)\}$ is linearly dependent in \mathbb{R}^3 .
- (ii) Show that $\{(1, 2, 2), (2, 1, 2), (2, 2, 1)\}$ is linearly independent in \mathbb{R}^3 .
- (iii) Show that $\{(0, 1, 1), (1, 0, 1), (1, 1, 0)\}$ is a basis of \mathbb{R}^3 .

Solution

(i) We supply the relation

$$\begin{pmatrix} 2\\1\\1 \end{pmatrix} + \begin{pmatrix} 1\\2\\2 \end{pmatrix} - 3 \begin{pmatrix} 1\\1\\1 \end{pmatrix} = \mathbf{0}.$$

(ii) Let $c_1, c_2, c_3 \in \mathbb{R}$ such that

$$c_1\begin{pmatrix}1\\2\\2\end{pmatrix}+c_2\begin{pmatrix}2\\1\\2\end{pmatrix}+c_3\begin{pmatrix}2\\2\\1\end{pmatrix}=\mathbf{0}$$

We obtain the system of linear equations

$$c_1 + 2c_2 + 2c_3 = 0, (1)$$

$$2c_1 + c_2 + 2c_3 = 0, (2)$$

$$2c_1 + 2c_2 + c_3 = 0. (3)$$

Now, $(1) + (2) - \frac{3}{2}(3)$ gives $\frac{5}{2}c_3 = 0$. Hence, from (1) and (2), $c_1 = -2c_2 = -2(-2c_1)$, from which we have $c_1 = c_2 = c_3 = 0$. Moreover, Cramer's rule tells us that this solution is unique, since the determinant

$$\begin{vmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{vmatrix} = (1+8+8) - (4+4+4) = 5 \neq 0.$$

This proves that the given set of vectors are linearly independent.

(iii) Let $c_1, c_2, c_3 \in \mathbb{R}$ such that

$$c_1 \begin{pmatrix} 0\\1\\1 \end{pmatrix} + c_2 \begin{pmatrix} 1\\0\\1 \end{pmatrix} + c_3 \begin{pmatrix} 1\\1\\0 \end{pmatrix} = \mathbf{0}.$$

We obtain the system of linear equations

$$c_2 + c_3 = 0, (1)$$

$$c_1 + c_3 = 0,$$
 (2)

 $c_1 + c_2 = 0.$ (3)

Now, (1) + (2) - (3) gives $2c_3 = 0$. Hence, from (1) and (2), $c_1 = c_2 = c_3 = 0$. Moreover, Cramer's rule tells us that this solution is unique, since the determinant

$$\begin{vmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{vmatrix} = (0+1+1) - (0+0+0) = 2 \neq 0.$$

This proves that the given set of vectors are linearly independent.

Let $v = (v_1, v_2, v_3) \in \mathbb{R}^3$ be arbitrary. We seek $a_1, a_2, a_3 \in \mathbb{R}$ such that

$$a_1 \begin{pmatrix} 0\\1\\1 \end{pmatrix} + a_2 \begin{pmatrix} 1\\0\\1 \end{pmatrix} + a_3 \begin{pmatrix} 1\\1\\0 \end{pmatrix} = v.$$

Like before, this is equivalent to solving the system of linear equations

$$a_2 + a_3 = v_1,$$

 $a_1 + a_3 = v_2,$
 $a_1 + a_2 = v_3,$

whose solution exists and is unique from Cramer's rule. It is easily verified that

$$2a_1 = -v_1 + v_2 + v_3, 2a_2 = v_1 - v_2 + v_3, 2a_3 = v_1 + v_2 - v_3.$$

Hence, any vector $v \in \mathbb{R}^3$ is uniquely expressible in terms of the given vectors, which proves that they are a basis of \mathbb{R}^3 .

Problem 9 Let $T, S: \mathbb{R}^2 \to \mathbb{R}^2$ be defined by T(x, y) = (x, 0) and S(x, y) = (0, y), where $x, y \in \mathbb{R}$. Find the mappings $S \circ T$ and $T \circ S$. Let [L] be the matrix representation of a linear mapping L in the standard basis. Check that $[S \circ T] = [S][T]$, with respect to the standard basis of \mathbb{R}^2 .

Solution Let $x, y \in \mathbb{R}$ be arbitrary. We have $(S \circ T), (T \circ T) \colon \mathbb{R}^2 \to \mathbb{R}^2$,

$$\begin{split} (S \circ T)(x,y) \;&=\; S(T(x,y)) \;=\; S(x,0) \;=\; (0,0), \\ (T \circ S)(x,y) \;&=\; T(S(x,y)) \;=\; T(0,y) \;=\; (0,0). \end{split}$$

In the standard basis of \mathbb{R}^2 ,

$$T(1,0) = (1,0), T(0,1) = (0,0), S(1,0) = (0,0), S(0,1) = (0,1), (S \circ T)(1,0) = (0,0), (S \circ T)(0,1) = (0,0).$$

Hence,

$$[T] = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \qquad [S] = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \qquad [S \circ T] = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}.$$

It is easily verified that

$$\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}.$$

Hence, $[S \circ T] = [S][T]$.

Problem 10 Let $T: \mathbb{R}^3 \to \mathbb{R}^2$, such that T(x, y, z) = (3x - 2y + z, x - 3y - 2z), for $x, y, z \in \mathbb{R}^3$. Find [T] with respect to the standard bases of \mathbb{R}^3 and \mathbb{R}^2 .

Solution We calculate

$$T(1,0,0) = (3,1),$$
 $T(0,1,0) = (-2,-3),$ $T(0,0,1) = (1,-2)$

Hence, we have

$$[T] = \begin{pmatrix} 3 & -2 & 1 \\ 1 & -3 & -2 \end{pmatrix}.$$

Problem 11 Let $T: \mathbb{R}^3 \to \mathbb{R}^2$, and let $\beta = \{(0,1,1), (1,0,1), (1,1,0)\}$ and $\gamma = \{(1,0), (1,1)\}$ be bases of \mathbb{R}^3 and \mathbb{R}^2 respectively. Let

$$[T]^{\gamma}_{\beta} = \begin{pmatrix} 1 & 2 & 4 \\ 2 & 1 & 0 \end{pmatrix}$$

be the matrix representation of T in the bases β and γ . Find T(x, y, z).

Solution We have

We reuse the calculation in Problem 8(iii) to note that the coordiantes of an arbitrary vector $v = (x, y, z) \in \mathbb{R}^3$, in the basis β are given by $[v]_{\beta} = ((y + z - x)/2, (x + z - y)/2, (x + y - z)/2)$. Hence,

$$T(x,y,z) = \frac{1}{2}(y+z-x)(3,2) + \frac{1}{2}(x+z-y)(3,1) + \frac{1}{2}(x+y-z)(4,0) = \left(2x+2y+z,\frac{1}{2}(-x+y+3z)\right).$$